Trustworthy Machine Learning

PAC Conformal Prediction

Sangdon Park

POSTECH

Motivation: Conditional Guarantee?



Conditional validity of inductive conformal predictors

Authors Vladimir Vovk

Publication date 2012/11/17

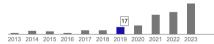
Conference Asian conference on machine learning

Pages 475-490

Publisher PMLR

Description Conformal predictors are set predictors that are automatically valid in the sense of having coverage probability equal to or exceeding a given confidence level. Inductive conformal predictors are a computationally efficient version of conformal predictors satisfying the same property of validity. However, inductive conformal predictors have been only known to control unconditional coverage probability. This paper explores various versions of conditional validity and various ways to achieve them using inductive conformal predictors and their modifications.

Total citations Cited by 251



Scholar articles

Conditional validity of inductive conformal predictors V Vovk - Asian conference on machine learning, 2012 Cited by 251 Related articles All 19 versions

Marginal Guarantee:

$$\mathbb{P}\left\{Y_{n+1} \in \hat{C}(X_{n+1})\right\} \ge 1 - \alpha$$

Marginal Guarantee:

$$\mathbb{P}\left\{Y_{n+1} \in \hat{C}(X_{n+1})\right\} \ge 1 - \alpha$$

X-conditional Guarantee:

$$\mathbb{P}\left\{Y_{n+1} \in \hat{C}(x) \middle| X_{n+1} = x\right\} \ge 1 - \alpha$$

Marginal Guarantee:

$$\mathbb{P}\left\{Y_{n+1} \in \hat{C}(X_{n+1})\right\} \ge 1 - \alpha$$

X-conditional Guarantee:

$$\mathbb{P}\left\{Y_{n+1} \in \hat{C}(x) \middle| X_{n+1} = x\right\} \ge 1 - \alpha$$

• Hopeless :([Lei and Wasserman, 2014]

Marginal Guarantee:

$$\mathbb{P}\left\{Y_{n+1} \in \hat{C}(X_{n+1})\right\} \ge 1 - \alpha$$

X-conditional Guarantee:

$$\mathbb{P}\left\{Y_{n+1} \in \hat{C}(x) \middle| X_{n+1} = x\right\} \ge 1 - \alpha$$

• Hopeless :([Lei and Wasserman, 2014]

Training-conditional Guarantee (=PAC Guarantee):

$$\mathbb{P}\left\{\mathbb{P}\left\{y \in \hat{C}(x)\right\} \ge 1 - \varepsilon\right\} \ge 1 - \delta$$

Marginal Guarantee:

$$\mathbb{P}\left\{Y_{n+1} \in \hat{C}(X_{n+1})\right\} \ge 1 - \alpha$$

X-conditional Guarantee:

$$\mathbb{P}\left\{Y_{n+1} \in \hat{C}(x) \middle| X_{n+1} = x\right\} \ge 1 - \alpha$$

• Hopeless :([Lei and Wasserman, 2014]

Training-conditional Guarantee (=PAC Guarantee):

$$\mathbb{P}\left\{\mathbb{P}\left\{y \in \hat{C}(x)\right\} \ge 1 - \varepsilon\right\} \ge 1 - \delta$$

We will explore this!

$$\mathbb{P}\left\{\mathbb{P}\left\{y\notin\hat{C}(x)\right\}\leq\varepsilon\right\}\geq1-\delta$$

PAC-style coverage guarantee

$$\mathbb{P}\left\{\mathbb{P}\!\left\{y\notin\hat{C}(x)\right\}\leq\varepsilon\right\}\geq1-\delta$$

• This implies that we need the i.i.d. assumption.

$$\mathbb{P}\left\{\mathbb{P}\left\{y\notin\hat{C}(x)\right\}\leq\varepsilon\right\}\geq1-\delta$$

- This implies that we need the i.i.d. assumption.
- \hat{C} is learned from a calibration set $Z_n \sim \mathcal{D}^n$.

$$\mathbb{P}\left\{\mathbb{P}\left\{y\notin\hat{C}(x)\right\}\leq\varepsilon\right\}\geq1-\delta$$

- This implies that we need the i.i.d. assumption.
- \hat{C} is learned from a calibration set $Z_n \sim \mathcal{D}^n$.
- We will interpret conformal prediction to a learning problem [Valiant, 1984].
 - ► See tolerance region [Wilks, 1941] and training-conditional inductive conformal prediction [Vovk, 2013] for an equivalent result.

$$\mathbb{P}\left\{\mathbb{P}\left\{y\notin\hat{C}(x)\right\}\leq\varepsilon\right\}\geq1-\delta$$

- This implies that we need the i.i.d. assumption.
- \hat{C} is learned from a calibration set $Z_n \sim \mathcal{D}^n$.
- We will interpret conformal prediction to a learning problem [Valiant, 1984].
 - ► See tolerance region [Wilks, 1941] and training-conditional inductive conformal prediction [Vovk, 2013] for an equivalent result.
- The main goal is to find a PAC learning algorithm for the set of conformal sets.

Learning-theoretic View [Park et al., 2020]

$$C(x) \coloneqq \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

Learning-theoretic View [Park et al., 2020]

Parameterized conformal sets

$$C(x) := \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

• How to find τ that satisfies the PAC guarantee?

Learning-theoretic View [Park et al., 2020]

$$C(x) := \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

- How to find τ that satisfies the PAC guarantee?
 - Finding a PAC learning algorithm

Learning-theoretic View [Park et al., 2020]

$$C(x) := \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

- How to find τ that satisfies the PAC guarantee?
 - Finding a PAC learning algorithm
 - Why not use $\tau = 0$?

Learning-theoretic View [Park et al., 2020]

$$C(x) := \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

- How to find τ that satisfies the PAC guarantee?
 - Finding a PAC learning algorithm
 - Why not use $\tau = 0$?
 - ★ No! Produces trivial conformal sets.

Learning-theoretic View [Park et al., 2020]

$$C(x) := \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

- How to find τ that satisfies the PAC guarantee?
 - ► Finding a PAC learning algorithm
 - Why not use $\tau = 0$?
 - ★ No! Produces trivial conformal sets.
- How to minimize the size of conformal sets?

Learning-theoretic View [Park et al., 2020]

$$C(x) := \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

- How to find τ that satisfies the PAC guarantee?
 - ► Finding a PAC learning algorithm
 - Why not use $\tau = 0$?
 - ★ No! Produces trivial conformal sets.
- How to minimize the size of conformal sets?
 - Another objective of the PAC learning algorithm

Learning-theoretic View [Park et al., 2020]

$$C(x) \coloneqq \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

- How to find τ that satisfies the PAC guarantee?
 - ► Finding a PAC learning algorithm
 - Why not use $\tau = 0$?
 - * No! Produces trivial conformal sets.
- How to minimize the size of conformal sets?
 - Another objective of the PAC learning algorithm
 - Minimize the size, while satisfying the PAC guarantee.

Secondary goal: minimizing set size

 $\mbox{maximizing } \tau \quad \Longrightarrow \quad \mbox{minimizing the expected set size}$

Secondary goal: minimizing set size

maximizing
$$au \implies ext{minimizing the expected set size}$$

• Recall the conformal set definition:

$$C_{\tau}(x) \coloneqq \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

Secondary goal: minimizing set size

maximizing
$$au \implies$$
 minimizing the expected set size

Recall the conformal set definition:

$$C_{\tau}(x) \coloneqq \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

We have

$$\tau_1 \le \tau_2 \implies \forall x, C_{\tau_2}(x) \subseteq C_{\tau_1}(x),$$

i.e., size is monotonically decreasing in τ .

Secondary goal: minimizing set size

maximizing
$$au \implies ext{minimizing the expected set size}$$

Recall the conformal set definition:

$$C_{\tau}(x) \coloneqq \{ y \in \mathcal{Y} \mid f(x, y) \ge \tau \}$$

We have

$$\tau_1 \le \tau_2 \implies \forall x, C_{\tau_2}(x) \subseteq C_{\tau_1}(x),$$

i.e., size is monotonically decreasing in τ .

ullet Maximizing au eventually minimizes the expected size, *i.e.*,

$$\mathbb{E}\left\{S(C(x))\right\} \le \sup_{x} S(C(x))$$

 $ightharpoonup S(\cdot)$: a size metric

$$\mathcal{A}_{\mathsf{Binom}}: \qquad \hat{ au} = \max_{ au \in \mathbb{R}_{\geq 0}} \ au \qquad \mathsf{subj. to} \qquad U_{\mathsf{Binom}}(C_{ au}, Z_n, \delta) \leq arepsilon$$

• $\mathcal{A}_{\mathsf{Binom}}$ returns $\hat{\tau}=0$ if the constraint is infeasible.

$$\mathcal{A}_{\mathsf{Binom}}: \qquad \hat{ au} = \max_{ au \in \mathbb{R}_{\geq 0}} \ au \qquad \mathsf{subj. to} \qquad U_{\mathsf{Binom}}(C_{ au}, Z_n, \delta) \leq arepsilon$$

- $A_{\sf Binom}$ returns $\hat{\tau}=0$ if the constraint is infeasible.
- \bullet For the PAC guarantee, we need to bound $\mathbb{P}\{y\notin C_{\tau}(x)\}$

$$\mathcal{A}_{\mathsf{Binom}}: \qquad \hat{ au} = \max_{ au \in \mathbb{R}_{>0}} \ au \qquad \mathsf{subj. to} \qquad U_{\mathsf{Binom}}(C_{ au}, Z_n, \delta) \leq arepsilon$$

- $\mathcal{A}_{\mathsf{Binom}}$ returns $\hat{\tau} = 0$ if the constraint is infeasible.
- For the PAC guarantee, we need to bound $\mathbb{P}\{y \notin C_{\tau}(x)\}$
 - ▶ Bound the expected error via a concentration inequality!

$$\mathcal{A}_{\mathsf{Binom}}: \qquad \hat{ au} = \max_{ au \in \mathbb{R}_{>0}} \ au \qquad \mathsf{subj. to} \qquad U_{\mathsf{Binom}}(C_{ au}, Z_n, \delta) \leq arepsilon$$

- $\mathcal{A}_{\mathsf{Binom}}$ returns $\hat{\tau} = 0$ if the constraint is infeasible.
- For the PAC guarantee, we need to bound $\mathbb{P}\{y \notin C_{\tau}(x)\}$
 - Bound the expected error via a concentration inequality!
- ullet Recall that $U_{\mathsf{Binom}}(C_{ au}, Z_n, \delta)$ is the binomial tail bound, *i.e.*,

$$U_{\mathsf{Binom}}(C_{\tau}, Z_n, \delta) \coloneqq \inf \left\{ \theta \in [0, 1] \mid F(E_{\tau}; n, \theta) \le \delta \right\}$$

- ▶ $F(k; n, \varepsilon)$: the cumulative distribution function of the binomial distribution with n trials and success probability ε
- $E_{\tau} \coloneqq \sum_{i=1}^{n} \mathbb{1} \left(y_i \notin C_{\tau}(x_i) \right)$

Theorem (Vovk [2013], Park et al. [2020])

The algorithm A_{Binom} is PAC, i.e., for any f, $\varepsilon \in (0,1)$, $\delta \in (0,1)$, and $n \in \mathbb{Z}_{\geq 0}$, we have

$$\mathbb{P}\left\{\mathbb{P}\left\{y\notin\hat{C}(x)\right\}\leq\varepsilon\right\}\geq1-\delta,$$

where the inner probability is taken over a labeled example $(x,y) \sim \mathcal{D}$, the outer probability is taken over i.i.d. labeled examples $Z_n \sim \mathcal{D}^n$, and $\hat{C} = \mathcal{A}_{Binom}(Z_n)$.

Theorem (Vovk [2013], Park et al. [2020])

The algorithm A_{Binom} is PAC, i.e., for any f, $\varepsilon \in (0,1)$, $\delta \in (0,1)$, and $n \in \mathbb{Z}_{\geq 0}$, we have

$$\mathbb{P}\left\{\mathbb{P}\left\{y\notin\hat{C}(x)\right\}\leq\varepsilon\right\}\geq1-\delta,$$

where the inner probability is taken over a labeled example $(x,y) \sim \mathcal{D}$, the outer probability is taken over i.i.d. labeled examples $Z_n \sim \mathcal{D}^n$, and $\hat{C} = \mathcal{A}_{Binom}(Z_n)$.

• Vovk [2013] provides the original proof.

Theorem (Vovk [2013], Park et al. [2020])

The algorithm A_{Binom} is PAC, i.e., for any f, $\varepsilon \in (0,1)$, $\delta \in (0,1)$, and $n \in \mathbb{Z}_{\geq 0}$, we have

$$\mathbb{P}\left\{\mathbb{P}\left\{y \notin \hat{C}(x)\right\} \le \varepsilon\right\} \ge 1 - \delta,$$

where the inner probability is taken over a labeled example $(x,y) \sim \mathcal{D}$, the outer probability is taken over i.i.d. labeled examples $Z_n \sim \mathcal{D}^n$, and $\hat{C} = \mathcal{A}_{Binom}(Z_n)$.

- Vovk [2013] provides the original proof.
- Park et al. [2020] interpret it in a learning-theoretic view

Theorem (Vovk [2013], Park et al. [2020])

The algorithm A_{Binom} is PAC, i.e., for any f, $\varepsilon \in (0,1)$, $\delta \in (0,1)$, and $n \in \mathbb{Z}_{\geq 0}$, we have

$$\mathbb{P}\left\{\mathbb{P}\left\{y\notin\hat{C}(x)\right\}\leq\varepsilon\right\}\geq1-\delta,$$

where the inner probability is taken over a labeled example $(x,y) \sim \mathcal{D}$, the outer probability is taken over i.i.d. labeled examples $Z_n \sim \mathcal{D}^n$, and $\hat{C} = \mathcal{A}_{Binom}(Z_n)$.

- Vovk [2013] provides the original proof.
- Park et al. [2020] interpret it in a learning-theoretic view
- Park and Kim [2023] provide a simplified proof.

PAC Guarantee: A Proof Sketch

Define:

- C_{τ} : a prediction set C with a parameter τ
- $L(C_{\tau}) := \mathbb{P}\{y \notin C_{\tau}(x)\}$ $\mathcal{H}_{\varepsilon} := \{\tau \in \mathbb{R}_{\geq 0} \mid L(C_{\tau}) > \varepsilon\}$ Suppose that $\mathbb{R}_{\geq 0}$ is a set of finely quantized real numbers.
- \bullet $\tau^* := \inf \mathcal{H}_{\epsilon}$

We have:

$$\mathbb{P}\Big\{L(C_{\mathcal{A}_{\mathsf{Binom}}(Z)}) > \varepsilon\Big\} \leq \mathbb{P}\Big\{\exists \tau \in \mathcal{H}_{\varepsilon}, U_{\mathsf{Binom}}(C_{\tau}, Z, \delta) \leq \varepsilon\Big\} \\
\leq \mathbb{P}\Big\{U_{\mathsf{Binom}}(C_{\tau^*}, Z, \delta) \leq \varepsilon\Big\} \\
\leq \mathbb{P}\Big\{L(C_{\tau^*}) > \varepsilon \wedge U_{\mathsf{Binom}}(C_{\tau^*}, Z, \delta) \leq \varepsilon\Big\} \\
\leq \mathbb{P}\Big\{L(C_{\tau^*}) > U_{\mathsf{Binom}}(C_{\tau^*}, Z, \delta)\Big\} \\
\leq \delta, \tag{2}$$

- (1): $\mathbb{1}(y \notin C_{\tau}(x))$ and U_{Binom} are non-decreasing in τ (i.e., Lemma 2 in [Park et al., 2022])
- (2): the property of the binomial tail bound U_{Binom} .

Application: Image Classification

Qualitative Results

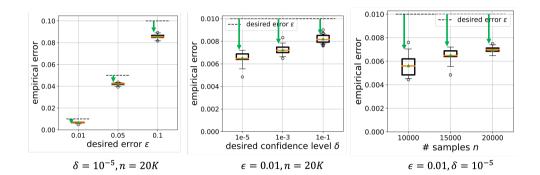


label: predicted label, green: true label

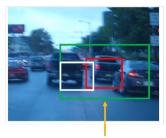
• As an image (and a model's understanding) is uncertain, the set size gets larger.

Application: Image Classification

Quantitative Results



Application: Regression



A point prediction fails, but a "conformal set" contains the true bounding box

White: Ground truth, Red: a point prediction, Green: Over-approximation of a conformal set

 The visualized conformal set is the bounding box that covers all bounding boxes in a conformal set.

Conclusion

- PAC conformal prediction constructs a conformal set with the PAC guarantee.
 - ▶ This is conformal prediction conditioned on a calibration set.
- Interesting questions:
 - Can we consider group-conditional conformal prediction?

Reference I

- J. Lei and L. Wasserman. Distribution-free prediction bands for non-parametric regression. Journal of the Royal Statistical Society Series B: Statistical Methodology, 76(1):71–96, 2014.
- S. Park and T. Kim. Pac neural prediction set learning to quantify the uncertainty of generative language models. *arXiv* preprint *arXiv*:2307.09254, 2023.
- S. Park, O. Bastani, N. Matni, and I. Lee. Pac confidence sets for deep neural networks via calibrated prediction. In *International Conference on Learning Representations*, 2020. URL https://openreview.net/forum?id=BJxVI04YvB.
- S. Park, E. Dobriban, I. Lee, and O. Bastani. PAC prediction sets under covariate shift. In *International Conference on Learning Representations*, 2022. URL https://openreview.net/forum?id=DhP9L8vIyLc.
- L. G. Valiant. A theory of the learnable. *Communications of the ACM*, 27(11):1134–1142, 1984.

Reference II

- V. Vovk. Conditional validity of inductive conformal predictors. *Machine learning*, 92(2-3): 349–376, 2013.
- S. S. Wilks. Determination of sample sizes for setting tolerance limits. *The Annals of Mathematical Statistics*, 12(1):91–96, 1941.